## Exercise 18

The figure shows a pendulum with length $L$ and the angle $\theta$ from the vertical to the pendulum. It can be shown that $\theta$, as a function of time, satisfies the nonlinear differential equation

$$
\frac{d^{2} \theta}{d t^{2}}+\frac{g}{L} \sin \theta=0
$$

where $g$ is the acceleration due to gravity. For small values of $\theta$ we can use the linear approximation $\sin \theta \approx \theta$ and then the differential equation becomes linear.
(a) Find the equation of motion of a pendulum with length 1 m if $\theta$ is initially 0.2 rad and the initial angular velocity is $d \theta / d t=1 \mathrm{rad} / \mathrm{s}$.
(b) What is the maximum angle from the vertical?
(c) What is the period of the pendulum (that is, the time to complete one back-and-forth swing)?
(d) When will the pendulum first be vertical?
(e) What is the angular velocity when the pendulum is vertical?


## Solution

For small angles, Newton's second law can be linearized as follows.

$$
\frac{d^{2} \theta}{d t^{2}}+\frac{g}{L} \theta=0, \quad \theta(0)=\theta_{0}, \quad \frac{d \theta}{d t}(0)=\omega_{0}
$$

This is a linear homogeneous ODE, so its solutions are of the form $\theta=e^{r t}$.

$$
\theta=e^{r t} \quad \rightarrow \quad \frac{d \theta}{d t}=r e^{r t} \quad \rightarrow \quad \frac{d^{2} \theta}{d t^{2}}=r^{2} e^{r t}
$$

Plug these formulas into the ODE.

$$
r^{2} e^{r t}+\frac{g}{L}\left(e^{r t}\right)=0
$$

Divide both sides by $e^{r t}$.

$$
r^{2}+\frac{g}{L}=0
$$

Solve for $r$.

$$
r=\left\{-i \sqrt{\frac{g}{L}}, i \sqrt{\frac{g}{L}}\right\}
$$

Two solutions to the ODE are $e^{-i \sqrt{g / L} t}$ and $e^{i \sqrt{g / L} t}$. By the principle of superposition, then,

$$
\begin{aligned}
\theta(t) & =C_{1} e^{-i \sqrt{g / L} t}+C_{2} e^{i \sqrt{g / L} t} \\
& =C_{1}\left(\cos \sqrt{\frac{g}{L}} t-i \sin \sqrt{\frac{g}{L}} t\right)+C_{2}\left(\cos \sqrt{\frac{g}{L}} t+i \sin \sqrt{\frac{g}{L}} t\right) \\
& =\left(C_{1}+C_{2}\right) \cos \sqrt{\frac{g}{L}} t+\left(-i C_{1}+i C_{2}\right) \sin \sqrt{\frac{g}{L}} t \\
& =C_{3} \cos \sqrt{\frac{g}{L}} t+C_{4} \sin \sqrt{\frac{g}{L}} t
\end{aligned}
$$

where $C_{3}$ and $C_{4}$ are arbitrary constants. Differentiate it with respect to $t$.

$$
\frac{d \theta}{d t}=-C_{3} \sqrt{\frac{g}{L}} \sin \sqrt{\frac{g}{L}} t+C_{4} \sqrt{\frac{g}{L}} \cos \sqrt{\frac{g}{L}} t
$$

Apply the initial conditions to determine $C_{3}$ and $C_{4}$.

$$
\begin{aligned}
\theta(0) & =C_{3}=\theta_{0} \\
\frac{d \theta}{d t}(0) & =C_{4} \sqrt{\frac{g}{L}}=\omega_{0}
\end{aligned}
$$

Solving this system yields

$$
C_{3}=\theta_{0} \quad \text { and } \quad C_{4}=\omega_{0} \sqrt{\frac{L}{g}} .
$$

The general solution is then

$$
\theta(t)=\theta_{0} \cos \sqrt{\frac{g}{L}} t+\omega_{0} \sqrt{\frac{L}{g}} \sin \sqrt{\frac{g}{L}} t .
$$

Therefore, plugging in $g=9.81 \mathrm{~m} / \mathrm{s}^{2}$ and $L=1 \mathrm{~m}$ and $\theta_{0}=0.2 \mathrm{rad}$ and $\omega_{0}=1 \mathrm{rad} / \mathrm{s}$,

$$
\theta(t) \approx 0.2 \cos 3.132 t+0.319 \sin 3.132 t
$$

The period is

$$
T=\frac{2 \pi}{\sqrt{\frac{g}{L}}}=2 \pi \sqrt{\frac{L}{g}} \approx 2.01 \mathrm{s.}
$$

In order to find the maximum angle, write the two terms as one in the formula for $\theta(t)$ by setting $A \cos \delta=\theta_{0}$ and $A \sin \delta=\omega_{0} \sqrt{L / g}$.

$$
\begin{aligned}
\theta(t) & =A \cos \delta \cos \sqrt{\frac{g}{L}} t+A \sin \delta \sin \sqrt{\frac{g}{L}} t \\
& =A\left(\cos \delta \cos \sqrt{\frac{g}{L}} t+\sin \delta \sin \sqrt{\frac{g}{L}} t\right) \\
& =A \cos \left(\sqrt{\frac{g}{L}} t-\delta\right)
\end{aligned}
$$

The amplitude $A$ is the maximum angle from the vertical; solve for it by squaring both sides of each defining equation and adding the respective sides.

$$
\begin{aligned}
A^{2} \cos ^{2} \delta+A^{2} \sin ^{2} \delta & =\left(\theta_{0}\right)^{2}+\left(\omega_{0} \sqrt{\frac{L}{g}}\right)^{2} \\
A^{2}\left(\cos ^{2} \delta+\sin ^{2} \delta\right) & =\theta_{0}^{2}+\frac{\omega_{0}^{2} L}{g} \\
A^{2} & =\theta_{0}^{2}+\frac{\omega_{0}^{2} L}{g}
\end{aligned}
$$

Plug in $g=9.81 \mathrm{~m} / \mathrm{s}^{2}$ and $L=1 \mathrm{~m}$ and $\theta_{0}=0.2 \mathrm{rad}$ and $\omega_{0}=1 \mathrm{rad} / \mathrm{s}$ to get the maximum angle from the vertical.

$$
A=\sqrt{\theta_{0}^{2}+\frac{\omega_{0}^{2} L}{g}} \approx 0.377 \mathrm{rad}
$$

Divide the two defining equations to get $\delta$, the phase angle.

$$
\begin{gathered}
\frac{A \sin \delta}{A \cos \delta}=\frac{\omega_{0} \sqrt{L / g}}{\theta_{0}} \\
\tan \delta=\frac{\omega_{0}}{\theta_{0}} \sqrt{\frac{L}{g}} \\
\delta=\tan ^{-1}\left(\frac{\omega_{0}}{\theta_{0}} \sqrt{\frac{L}{g}}\right) \approx 1.011 \mathrm{rad}
\end{gathered}
$$

The pendulum is first vertical when $\theta=0$ at the smallest positive value of $t$, that is, when the argument of cosine is $\pi / 2$.

$$
\sqrt{\frac{g}{L}} t-\delta=\frac{\pi}{2}
$$

Solve for $t$.

$$
t=\frac{\delta+\frac{\pi}{2}}{\sqrt{\frac{g}{L}}} \approx 0.824 \mathrm{~s}
$$

To find the angular velocity when the pendulum is vertical, take the derivative of $\theta(t)$

$$
\theta^{\prime}(t)=-\theta_{0} \sqrt{\frac{g}{L}} \sin \sqrt{\frac{g}{L}} t+\omega_{0} \cos \sqrt{\frac{g}{L}} t
$$

and evaluate it at $t \approx 0.824 \mathrm{~s}$, the time the pendulum is first vertical.

$$
\theta^{\prime}(0.824) \approx-1.18 \frac{\mathrm{rad}}{\mathrm{~s}}
$$

